

GAUGE-NATURAL TRANSFORMATIONS OF SOME COTANGENT BUNDLES

IVAN KOLÁŘ AND JIŘÍ TOMÁŠ

Dedicated to Anton Dekrét on the occasion of his 65-th birthday

ABSTRACT. For an arbitrary vector bundle $E \rightarrow M$, we determine all gauge-natural transformations $T^*E \rightarrow T^*E^*$. In order to describe the result geometrically, we characterize some properties of T^*E in terms of an original approach to the concept of double vector bundle.

In [4] and [7], some important relations between the cotangent bundle of the tangent bundle T^*TM and the cotangent bundle of the cotangent bundle T^*T^*M of a manifold M were studied and applied. In the present paper we discuss the "pure" case of the cotangent bundle T^*E of any vector bundle $E \rightarrow M$ and the cotangent bundle T^*E^* of its dual E^* . First of all we show that T^*E with the canonical projections to E and E^* has the structure of double vector bundle. The origin of such a concept goes back to [3], [6], [9], but our approach in Section 2 is new and we find it very simple. In Section 3 we construct a canonical isomorphism $\varepsilon : T^*E \rightarrow T^*E^*$. In the next section we use the viewpoint of the theory of gauge-natural bundles, [1], [2], and we determine all gauge-natural (in other words: geometrical) transformations $T^*E \rightarrow T^*E^*$. In Section 5 we clarify how the canonical isomorphism ε relates a linear vector field on E and the dual vector field on E^* . All manifolds and maps are assumed to be infinitely differentiable.

1. TWO VECTOR BUNDLE STRUCTURES ON T^*E

Consider a vector bundle $p : E \rightarrow M$ and its dual bundle $p^* : E^* \rightarrow M$. Write $q_1 : T^*E \rightarrow E$ for the cotangent bundle of E . According to [2], p.227, there exists another projection $q_2 : T^*E \rightarrow E^*$. For every linear map $w : T_y E \rightarrow \mathbb{R}$, $y \in E$, we define $q_2(w)$ to be the restriction of w to the vertical tangent space $V_y E$, which is canonically identified with the fiber E_x , $x = py$. Let x^i, y^p be some linear fiber coordinates on E and x^i, z_p be the dual coordinates on E^* . The additional coordinates on T^*E are given by $w = v_i dx^i + u_p dy^p$. Then the coordinate form of q_1 or q_2 is

$$(1) \quad q_1(x^i, y^p, u_p, v_i) = (x^i, y^p), \quad q_2(x^i, y^p, u_p, v_i) = (x^i, u_p)$$

1991 *Mathematics Subject Classification.* 53A55, 58A20.

Key words and phrases. Gauge-natural transformation, cotangent bundle of a vector bundle, double vector bundle.

The authors were supported by the grant No. 201/96/0079 of the GA ČR.

We are going to show that $q_2 : T^*E \rightarrow E^*$ is a vector bundle too. We shall use the well-known fact there are two vector bundle structures $\pi_E : TE \rightarrow E$ and $Tp : TE \rightarrow TM$ on TE , [2]. If $X^i = dx^i$, $Y^p = dy^p$ are the additional coordinates on TE , then $Tp(x^i, y^p, X^i, Y^p) = (x^i, X^i)$. The vector addition and the multiplication by reals on Tp have the following form

$$(2) \quad \begin{aligned} &(x^i, y_1^p, X^i, Y_1^p) + (x^i, y_2^p, X^i, Y_2^p) = (x^i, y_1^p + y_2^p, X^i, Y_1^p + Y_2^p), \\ &k(x^i, y^p, X^i, Y^p) = (x^i, ky^p, X^i, kY^p). \end{aligned}$$

Consider $w_1 \in T_{y_1}^*E$ and $w_2 \in T_{y_2}^*E$ satisfying $q_2(w_1) = q_2(w_2)$. Let us decompose, with respect to Tp , a vector $Y \in T_{y_1+y_2}E$ as $Y_1 + Y_2$, $Y_1 \in T_{y_1}E$, $Y_2 \in T_{y_2}E$, $Tp(Y) = Tp(Y_1) = Tp(Y_2)$. Then we define $w_1 + w_2 \in T_{y_1+y_2}^*E$ by

$$(3) \quad (w_1 + w_2)(Y) = w_1(Y_1) + w_2(Y_2)$$

The correctness follows from the coordinate form of (3). We have $Y = (x^i, y_1^p + y_2^p, X^i, Y^p)$, $Y_1 = (x^i, y_1^p, X^i, Y_1^p)$, $Y_2 = (x^i, y_2^p, X^i, Y_2^p)$ with $Y^p = Y_1^p + Y_2^p$ and $w_1 = (x^i, y_1^p, u_p, v_{1i})$, $w_2 = (x^i, y_2^p, u_p, v_{2i})$. Then $w_1(Y_1) + w_2(Y_2) = u_p Y_1^p + v_{1i} X^i + u_p Y_2^p + v_{2i} X^i = u_p Y^p + (v_{1i} + v_{2i}) X^i$. Moreover, the latter expression implies

$$(4) \quad (x^i, y_1^p, u_p, v_{1i}) + (x^i, y_2^p, u_p, v_{2i}) = (x^i, y_1^p + y_2^p, u_p, v_{1i} + v_{2i})$$

Further, if $w \in T_y^*E$, $0 \neq k \in \mathbb{R}$ and $Y \in T_yE$, we construct $\frac{1}{k}Y$ with respect to the vector bundle structure Tp . Hence $\frac{1}{k}Y \in T_yE$ and we set

$$(5) \quad (kw)(Y) = kw\left(\frac{1}{k}Y\right)$$

For $k = 0$, we consider the restriction T_0E of E to the zero section $0 : M \rightarrow E$ and the tangent map $T0 : TM \rightarrow TE$. We have the following decomposition $T_0E = TM \times_M E$. We set $pr_1 Y = Tp(Y)$. Then $Y - T0(pr_1 Y)$ is a vertical vector, which is identified with $pr_2 Y \in E$. Now we define $0w \in T_{0(x)}^*E$, $x = py$, by

$$(6) \quad (0w)(Y) = (q_2 w)(pr_2 Y), \quad Y \in T_{0(x)}E.$$

In coordinates, one finds easily

$$(7) \quad k(x^i, y^p, u_p, v_i) = (x^i, ky^p, u_p, kv_i), \quad k \in \mathbb{R}$$

Clearly, (4) and (7) imply, that $q_2 : T^*E \rightarrow E^*$ is a vector bundle.

2. DOUBLE VECTOR BUNDLES

We define a fibered square to be a commutative diagram

$$(8) \quad \begin{array}{ccc} & Y & \\ q_1 \swarrow & & \searrow q_2 \\ Y_1 & & Y_2 \\ p_1 \searrow & & \swarrow p_2 \\ & M & \end{array}$$

in which all arrows are fibered manifolds. If there is no danger of confusion, we shall write Y for (8). The diagonal map in (8) will be denoted by $q : Y \rightarrow M$. If $(\tilde{Y}, \tilde{Y}_1, \tilde{Y}_2, \tilde{M}, \tilde{q}_1, \tilde{q}_2, \tilde{p}_1, \tilde{p}_2)$ is another fibered square, then a morphism $Y \rightarrow \tilde{Y}$ means a quadruple of maps $f : Y \rightarrow \tilde{Y}$, $f_1 : Y_1 \rightarrow \tilde{Y}_1$, $f_2 : Y_2 \rightarrow \tilde{Y}_2$, $f_0 : M \rightarrow \tilde{M}$ such that all pairs (f, f_1) , (f, f_2) , (f_1, f_0) , (f_2, f_0) are fibered manifold morphisms. Hence we have a category \mathcal{FS} of fibered squares.

A fibered square will be called a vector bundle square, if all arrows in (8) are vector bundles. For example, both $(T^*E, E, E^*, M, q_1, q_2, p, p^*)$ and $(TE, E, TM, M, \pi_E, Tp, p, \pi_M)$ are vector bundle squares. An \mathcal{FS} -morphism (f, f_1, f_2, f_0) of two vector bundle squares is said to be linear, if all pairs (f, f_1) , (f, f_2) , (f_1, f_0) , (f_2, f_0) are vector bundle morphisms. Hence we obtain a category \mathcal{VBS} of vector bundle squares.

Consider a manifold M and three vector spaces V_1, V_2, V_3 . Put

$$(9) \quad Y = M \times V_1 \times V_2 \times V_3, \quad Y_1 = M \times V_1, \quad Y_2 = M \times V_2.$$

Then we have canonical vector bundle structures on $Y \rightarrow Y_1$, $Y \rightarrow Y_2$, $Y_1 \rightarrow M$ and $Y_2 \rightarrow M$. We shall say that $Y = M \times V_1 \times V_2 \times V_3$ is a trivial double vector bundle.

Definition 1. A vector bundle square (8) will be called a double vector bundle, if for every $x \in M$ there exists its neighbourhood $U \subset M$ such that $q^{-1}(U)$ is \mathcal{VBS} -isomorphic to a trivial double vector bundle.

A morphism between two double vector bundles is an \mathcal{VBS} -morphism. Thus, we obtain a category \mathcal{DVBS} of double vector bundles.

Denote by $HY \subset Y$ the set of elements which are projected by q_1 into a zero vector in Y_1 and by q_2 into a zero vector in Y_2 . By J. Pradines, [5], [6], HY is called the heart of the double vector bundle Y . In the trivial case we have $H(M \times V_1 \times V_2 \times V_3) = M \times V_3$. This implies that even in the general case both vector bundle structures q_1 and q_2 coincide on HY and $HY \rightarrow M$ is a vector bundle.

If $D \subset \mathbb{R}^m$ is an open subset and V is a vector space, then Section 1 implies

$$T^*(D \times V) = D \times V \times V^* \times \mathbb{R}^{m*}.$$

Quite similarly,

$$T(D \times V) = D \times V \times \mathbb{R}^m \times V.$$

Then one verifies easily

Proposition 1. For every vector bundle E , both TE and T^*E are double vector bundles.

We remark that a direct characterization of double vector bundles in terms of the underlying vector bundle structures can be deduced directly from the results of [8].

3. THE CANONICAL ISOMORPHISM $T^*E \rightarrow T^*E^*$

We are going to construct a canonical map $\varepsilon : T^*E \rightarrow T^*E^*$. Consider the evaluation map $e : E \times_M E^* \rightarrow \mathbb{R}$. Its differential

$$de : TE \times_{TM} TE^* \rightarrow \mathbb{R}$$

is the second component of the tangent map $Te : TE \times_{TM} TE^* \rightarrow T\mathbb{R} = \mathbb{R} \times \mathbb{R}$.

Proposition 2. *For every covector $C \in T_y^*E$, there exists a unique element $z \in E^*$ satisfying $py = p^*z$ and a unique covector $\varepsilon C \in T_z^*E^*$ such that every vectors $A \in T_yE$ and $B \in T_zE^*$ over the same vector $Tp(A) = Tp^*(B) \in TM$ satisfy*

$$(10) \quad de(A, B) = C(A) - (\varepsilon C)(B)$$

Proof. The coordinate form of the evaluation map e is $y^p z_p$, so that de is of the form

$$z_p dy^p + y^p dz_p.$$

Consider $C = (x^i, y^p, u_p, v_i)$, $A = (x^i, y^p, a^i, a^p)$, $B = (x^i, g_p, a^i, b_p)$ and write $D = (x^i, g_p, h^p, k_i)$. Then the condition $de(A, B) = C(A) - D(B)$ reads

$$g_p a^p + y^p b_p = v_i a^i + u_p a^p - h^p b_p - k_i a^i.$$

Since a^i , a^p and b_p are arbitrary, the unique $D = \varepsilon C$ is of the form

$$(11) \quad g_p = u_p, \quad h^p = -y^p, \quad k_i = v_i.$$

Definition 2. *The map (11) from Proposition 2 will be called the canonical isomorphism $\varepsilon : T^*E \rightarrow T^*E^*$.*

Clearly, ε is an isomorphism of double vector bundles.

4. ALL GAUGE-NATURAL TRANSFORMATIONS $T^*E \rightarrow T^*E^*$

Using the viewpoint of the theory of gauge-natural bundles, [1], [2], we can say that $\varepsilon : T^*E \rightarrow T^*E^*$ is a gauge-natural transformation. We are going to determine all gauge-natural transformations $T^*E \rightarrow T^*E^*$. For every $w \in T^*E$, we have $q_1(w) \in E$, $q_2(w) \in E^*$ and $p_1(q_1(w)) = p_2(q_2(w))$, so that we can evaluate $\langle q_1(w), q_2(w) \rangle \in \mathbb{R}$. Write $\eta \mapsto (k)_1 \eta$ or $\eta \mapsto (k)_2 \eta$, $k \in \mathbb{R}$, $\eta \in T^*E^*$, for the scalar multiplication with respect to the first or second vector bundle structure on T^*E^* , respectively.

Proposition 3. *All gauge-natural transformations $T^*E \rightarrow T^*E^*$ are of the form*

$$(12) \quad w \mapsto A(\langle q_1(w), q_2(w) \rangle)_1 B(\langle q_1(w), q_2(w) \rangle)_2 \varepsilon(w),$$

where $A(t)$ and $B(t)$ are two arbitrary smooth functions of one variable.

Proof. As remarked in [2], p.409, the category $\mathcal{VB}_{m,n}$ of vector bundles with m -dimensional bases and n -dimensional fibers and their local isomorphisms is naturally equivalent to the category $\mathcal{PB}_m(GL(n))$ of $GL(n)$ -principal bundles with m -dimensional bases and their local isomorphisms. Consider the trivial vector bundle

$\mathbb{R}^m \times \mathbb{R}^n$ and write $S = (T^*(\mathbb{R}^m \times \mathbb{R}^n))_0$ and $Z = (T^*(\mathbb{R}^m \times \mathbb{R}^{n*}))_0$, $0 \in \mathbb{R}^m$. Then both S and Z are $W_m^1 GL(n)$ -spaces and all gauge-natural transformations $T^*E \rightarrow T^*E^*$ are in the bijection with the $W_m^1 GL(n)$ -equivariant maps $S \rightarrow Z$, [2], Chapter XII.

On S , we have the coordinates y^p, u_p, v_i from Section 1. Every element of $T^*(\mathbb{R}^m \times \mathbb{R}^{n*})$ can be written in the form $\xi_i dx^i + \mu^p dz_p$, so that z_p, μ^p, ξ_i are the corresponding coordinates on Z . The elements of $W_m^1 GL(n)$ are of the form (a_j^i, a_q^p, a_{qi}^p) , $\det a_j^i \neq 0$, $\det a_q^p \neq 0$, [2], p.153. Using standard evaluations, one finds easily the following actions of $W_m^1 GL(n)$ on S and Z

$$(13) \quad \bar{y}^p = a_q^p y^q, \quad \bar{u}_p = \tilde{a}_p^q u_q, \quad \bar{v}_i = \tilde{a}_i^j v_j - \tilde{a}_i^j \tilde{a}_r^p a_{qj}^r u_p y^q$$

$$(14) \quad \bar{z}_p = \tilde{a}_p^q z_q, \quad \bar{\mu}^p = a_q^p \mu^q, \quad \bar{\xi}_i = \tilde{a}_i^j \xi_j + \tilde{a}_i^j \tilde{a}_r^p a_{qj}^r z_p \mu^q$$

where \tilde{a}_j^i or \tilde{a}_q^p is the inverse matrix to a_j^i or a_q^p , respectively. To determine all $W_m^1 GL(n)$ -equivariant maps $f : S \rightarrow Z$, we shall use the methods from [2]. Thus, let us start from an arbitrary map

$$(15) \quad z_p = f_p(y, u, v), \quad \mu^p = f^p(y, u, v), \quad \xi_i = f_i(y, u, v).$$

Consider first the equivariancy with respect to the canonical injection $GL(m) \times GL(n) \rightarrow W_m^1 GL(n)$, which is characterized by $a_{qi}^p = 0$. Using the homotheties in $GL(m)$, we find that f_p and f^p are independent of v and f_i is linear in v_i . The equivariancy with respect to the whole group $GL(m)$ yields

$$(16) \quad f_i = g(y, u) v_i.$$

Then we consider equivariancy with respect to $GL(n)$. The tensor evaluation theorem, [2], Section 26, yields

$$(17) \quad f^p = -A(y^q u_q) y^p, \quad f_p = B(y^q u_q) v_p.$$

Consider now the equivariancy with respect to the kernel K of the canonical projection $W_m^1 GL(n) \rightarrow GL(m) \times GL(n)$, which is characterized by $a_j^i = \delta_j^i$, $a_q^p = \delta_q^p$. This yields

$$a_{qi}^p A u_p B y^q = a_{qi}^p g u_p y^q.$$

Thus,

$$(18) \quad g(y, u) = A(y^p u_p) B(y^q u_q)$$

Clearly, (16)-(18) is the coordinate form of (12). \square

5. LINEAR VECTOR FIELDS

In general, every vector field $X : N \rightarrow TN$ on a manifold N defines a function $\tilde{X} : T^*N \rightarrow \mathbb{R}$, $\tilde{X}(z) = \langle X(x), z \rangle$, $z \in T_x^*N$. Conversely, every function $f : T^*N \rightarrow \mathbb{R}$ linear on each fiber is of the form $f = \tilde{X}$ for a vector field $X : N \rightarrow TN$.

Consider a linear vector field $X : E \rightarrow TE$, [2], p.379. Its coordinate form is

$$X^i(x) \frac{\partial}{\partial x^i} + X_q^p(x) y^q \frac{\partial}{\partial y^p}.$$

Using flows, one constructs the dual vector field $X^* : E^* \rightarrow TE^*$, [2], p.380, whose coordinate expression is

$$X^i(x) \frac{\partial}{\partial x^i} - X_p^q(x) z_q \frac{\partial}{\partial z_p}.$$

Proposition 4. *For every linear vector field $X : E \rightarrow TE$, we have*

$$\tilde{X} = \tilde{X}^* \circ \varepsilon.$$

Proof. In the coordinates of the proof of Proposition 2, $\tilde{X} = X^i(x)v_i + X_q^p(x)y^q u_p$, $\tilde{X}^* = X^i(x)k_i - X_q^p(x)g_p h^q$. Then (11) yields our claim.

6. REMARK

It can be expected from the trivialization $T(D \times V^*) = D \times V^* \times \mathbb{R}^n \times V^*$, that there is no natural isomorphism $TE \rightarrow TE^*$. To confirm it rigorously, one can determine all gauge-natural transformations $TE \rightarrow TE^*$. Using the basic methods from [2], one obtains easily the following result. Consider the projection $Tp : TE \rightarrow TM$, the homothetic transformation $k_M : TM \rightarrow TM$, $v \mapsto kv$, $k \in \mathbb{R}$, and the tangent map $T0 : TM \rightarrow TE^*$ of the zero section $0 : M \rightarrow E^*$. All gauge-natural transformations $TE \rightarrow TE^*$ are of the form

$$T0 \circ k_M \circ Tp : TE \rightarrow TE^*, \quad k \in \mathbb{R}.$$

Clearly, none of them is an isomorphism.

REFERENCES

- [1] Eck D. J., *Gauge-natural bundles and generalized gauge theories*, Mem. Amer. Math. Soc. **247** (1981).
- [2] Kolář I., Michor P. W., Slovák J., *Natural Operations in Differential Geometry*, Springer – Verlag, 1993.
- [3] Kolář I., Modugno M., *On the algebraic structure on the jet prolongations of fibered manifolds*, Czechoslovak Math. J. **40** (1990), 601-611.
- [4] Kolář I., Radziszewski Z., *Natural Transformations of Second Tangent and Cotangent Bundles*, Czechoslovak Math. J. (1988), 274-279.
- [5] Libermann P., *Introduction to the theory of semi-holonomic jets*, to appear in Arch. Math. (Brno).
- [6] Pradines J., *Représentation des jets non holonomes par des morphismes vectoriels doubles soudés*, CRAS Paris série **278** (1974), 1557-1560.

- [7] Tomáš J., *Natural operators on vector fields on the cotangent bundles of the bundles of (k, r) -velocities*, to appear in Rendiconti del Circolo Matematico di Palermo.
- [8] Vanžurová A., *Double vector spaces*, Acta Univ. Palackianae Olomouensis **88** (1987), 9-25.
- [9] White J. E., *The methods of iterated tangents with applications to local Riemannian geometry*, Pitman Press (1982).

(Received April 20, 1997)

Department of Algebra and Geometry
Faculty of Science
Masaryk University
Janáčkovo nám. 2a
662 95 Brno
CZECH REPUBLIC

Department of Mathematics
Faculty of Civil Engineering
Technical University Brno
Žižkova 17
602 00 Brno
CZECH REPUBLIC