

# EXISTENCE OF INVARIANT TORI OF CRITICAL DIFFERENTIAL EQUATION SYSTEMS DEPENDING ON MORE-DIMENSIONAL PARAMETER. PART I.

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*Dedicated to Anton Dekrét on the occasion of his 65-th birthday*

ABSTRACT. In the paper a system of differential equations depending on more-dimensional parameter with the matrix of the first linear approximation  $P$  having pure imaginary eigenvalues while the others do not lie on the imaginary axis is studied. Conditions under which such a system has invariant tori are presented (section 1). In sections 2, 3 the cases when  $P$  has one and two pairs of pure imaginary eigenvalues are investigated. In Part II the cases with three and four pairs of pure imaginary eigenvalues will be analysed.

## Introduction

In the monograph [1] Yu. N. Bibikov studies the system of differential equations depending on a small non-negative parameter  $\mu$ :

$$(1) \quad \dot{x} = X(x, \mu) + X^*(x, \mu) ,$$

where  $x = (x_1, \dots, x_n)$ ,  $X(x, \mu)$  - a vector polynomial with respect to  $x, \mu$ ,  $X(0, 0) = 0$ ,  $X^*(x, \mu) : \mathbb{M} \rightarrow \mathbb{R}^n$ ,  $M = \{(x, \mu) : \|x\| < K, 0 \leq \mu < L\}$  - a continuous vector function with the property:

$$X^*(\sqrt{\mu}x, \mu) = (\sqrt{\mu})^{3p+2} \tilde{X}(x, \mu) ,$$

$p$  - a natural number,  $\tilde{X}(x, \mu)$  - a function of the class  $C_{x\mu}^{10}(\mathbb{M})$ . It is supposed that the spectrum of the linear approximation matrix  $P$  of the polynomial  $X(x, \mu)$  consists of  $m$  pairs of pure imaginary eigenvalues while the others have non-zero real parts. Yu. N. Bibikov found conditions under which to every small parameter  $\mu$  there exists an invariant manifold of the system (1) that is homeomorphic with a torus. He also presents in [1] an idea how these results can be utilized in the case when the parameter  $\mu$  is  $m$ -dimensional one, where  $m$  is the number of the pairs of pure imaginary eigenvalues of the matrix  $P$ .

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In applications the dimension of the parameter  $\mu$  is not a function of the number of pure imaginary eigenvalues of  $P$  but it follows from the character of a process which is described by the considered system. Therefore it is worth studying the system (1) which depend on the more-dimensional parameter  $\mu$  with an arbitrary dimension.

In this article the system (1) is investigated on the domain:

$$(2) \quad \mathbb{M} = \{(x, y) : x = (x_1, \dots, x_n), \mu = (\mu_1, \dots, \mu_d), d \geq 1, \|x\| < K, \|\mu\| < L\}$$

(in the whole article Euclidean norm is used).

Let us take an arbitrary parameter  $\mu \in \mathbb{M}$ . Consider the beam  $\delta(\mu_0) = \{\varepsilon\mu_0 : 0 \leq \varepsilon < L, \mu_0 = \frac{\mu}{\|\mu\|}\}$  (index "o" at parameters  $\mu$  will always have this meaning). The system (1) depending on parameters  $\mu \in \delta(\mu_0)$  has the form:

$$(3) \quad \dot{x} = X(x, \varepsilon\mu_0) + X^*(x, \varepsilon\mu_0), \quad 0 \leq \varepsilon < L.$$

The system (3) is the system of differential equations depending on one-dimensional non-negative parameter  $\varepsilon$ . It means the system (3) is the system of the kind (1) which was studied in [1]. Such an access enables to investigate the system (1) on the domain (2) and utilize the results achieved in [1]. Doing it the problem of determining subsets of the set  $\mathbb{M}$  with respect to  $\mu$  on which invariant manifolds of the system (1) exist arises.

In section 1 preliminary transformations of the system (1) depending on parameters  $\mu$  from the domain (2) are performed enabling to utilize the results from [1]. In sections 2, 3 the cases when the matrix  $P$  has one and two pairs of pure imaginary eigenvalues are studied.

## 1. The existence of invariant tori

Consider the system of differential equations

$$(1.1) \quad \dot{x} = X(x, \mu) + X^*(x, \mu),$$

where  $x = (x_1, \dots, x_n)$ ,  $\mu = (\mu_1, \dots, \mu_d)$ ,  $\dot{x} = \frac{dx}{dt}$ ,  $X(x, \mu)$  - a vector polynomial with respect to  $x, \mu$ ,  $X(0, 0) = 0$ ,  $X^*(x, \mu) : \mathbb{M} \rightarrow \mathbb{R}^n$ ,  $\mathbb{M} = \{x, \mu\} : \|x\| < K, \|\mu\| < L\}$  - a continuous function with the property:

$$(1.2) \quad X^*(\sqrt{\varepsilon}x, \varepsilon\mu_0) = (\sqrt{\varepsilon})^{3p+2} \tilde{X}(x, \varepsilon, \mu_0),$$

$0 \leq \varepsilon < L$ ,  $\mu \in \mathbb{M}$ ,  $p$  - a natural number,  $\tilde{X}(x, \varepsilon, \mu_0)$  - a continuous function with respect to  $x, \varepsilon, \mu_0$  of the class  $C_x^1(\mathbb{M})$ .

We suppose that the matrix  $P = \frac{\partial X(0,0)}{\partial x}$  has  $m$  pairs of pure imaginary eigenvalues  $\pm i\lambda_1, \dots, \pm i\lambda_m$  and the others  $\lambda_{2m+1}, \dots, \lambda_n$  have non-zero real parts. Further we suppose that  $\det P \neq 0$ .

**Note 1.1.** The requirements on the functions  $X(x, \mu)$ ,  $X^*(x, \mu)$  in (1.1) are not very limiting as every system  $\dot{x} = f(x, \mu)$ ,  $f(x, \mu) \in C^{3p+3}(\mathbb{M})$ ,  $f(0, 0) = 0$ , can be expressed in the form (1.1). For that it is sufficient to introduce the function  $f(x, \mu)$  in the form of the Taylor polynomial with the Lagrange form of the remainder. In this case  $X(x, \mu) = \sum_{k=0}^N X_k(x_1, \dots, x_n) \mu_1^{k_1} \dots \mu_d^{k_d}$ ,  $k = k_1 + \dots + k_d$ ,  $N$  - the whole part of the number  $\frac{3p+1}{2}$ ,  $X_k(x_1, \dots, x_n)$  - polynomials of the degree not higher than  $3p+1-2k$ .

Let us denote  $F(x, \mu) = X(x, \mu) + X^*(x, \mu)$ . In the power of (1.2)  $F(0, 0) = 0$ . This means that the origin  $(x, \mu) = (0, 0)$  is the state of equilibrium of the system (1.1). Since

$$\begin{aligned} \frac{\partial X^*(x, \mu)}{\partial x} &= \frac{\partial X^*(\sqrt{\varepsilon}y, \varepsilon\mu_0)}{\partial x} = \frac{\partial}{\partial x} \left[ (\sqrt{\varepsilon})^{3p+2} \tilde{X}(y, \varepsilon, \mu_0) \right] = \\ &= \frac{\partial}{\partial y} \left[ (\sqrt{\varepsilon})^{3p+2} \tilde{X}(y, \varepsilon, \mu_0) \right] \cdot \frac{\partial y}{\partial x} = (\sqrt{\varepsilon})^{3p+1} \frac{\partial}{\partial y} \tilde{X}(y, \varepsilon, \mu_0) , \end{aligned}$$

we have:

$$\left| \frac{\partial F(0, 0)}{\partial x} \right| = \left| \frac{\partial X(0, 0)}{\partial x} + \frac{\partial X^*(0, 0)}{\partial x} \right| = |P| \neq 0 .$$

Using Implicit Function Theorem on the function  $F(x, \mu)$  we get that in a small neighbourhood  $O(0)$  of the origin  $\mu = 0$  there exists a function  $x = \psi(\mu)$  with the following properties:

1.  $\psi(0) = 0$
2.  $F[\psi(\mu), \mu] = 0$  for  $\mu \in O(0)$ .

We see that to every small enough parameter  $\mu^* \in \mathbb{M}$  there exists the state of equilibrium of the system (1.1)  $x^* = \psi(\mu^*)$ . It will be shown that to such a  $\mu^*$  there exists also under certain conditions an invariant manifold of the system (1.1) which is homeomorphic with a torus. When such a situation realizes we say that at  $\mu = 0$  the bifurcation of an invariant torus arises from the state of equilibrium  $x = 0$ .

**Lemma 1.1.** *System (1.1) can be reduced by the transformation*

$$(1.3) \quad x = S\xi + T\mu ,$$

where  $\xi = \text{col}(y, \bar{y}, z)$ ,  $y = \text{col}(y_1, \dots, y_m)$ ,  $y$  - the complex conjugate vector to  $y$  (in the article the symbol " $\bar{a}$ " always means the complex conjugate expression to  $a$ ,  $z = \text{col}(z_1, \dots, z_{n-2m})$ ,  $S$  - a regular  $n \times n$ -matrix,  $T$  -  $n \times d$ -matrix, to the system

$$(1.4) \quad \begin{aligned} \dot{y} &= i\lambda y + Y(y, \bar{y}, z, \mu) + Y^*(y, \bar{y}, z, \mu) \\ \dot{\bar{y}} &= i\lambda \bar{y} + \bar{Y}(y, \bar{y}, z, \mu) + \bar{Y}^*(y, \bar{y}, z, \mu) \\ \dot{z} &= Jz + Z(y, \bar{y}, z, \mu) + Z^*(y, \bar{y}, z, \mu) , \end{aligned}$$

where  $\lambda = \text{diag}(\lambda_1, \dots, \lambda_m)$ ,  $J$  - a Jordan canonical lower matrix,  $Y, \bar{Y}, Z$  - vector polynomials without scalar and linear terms,  $Y^*, \bar{Y}^*, Z^*$  - continuous functions having the property (1.2), i.e. for example

$$Y(\sqrt{\varepsilon}y, \sqrt{\varepsilon}\bar{y}, \sqrt{\varepsilon}z, \varepsilon\mu_0) = (\sqrt{\varepsilon})^{3p+2} \tilde{Y}(y, \bar{y}, z, \varepsilon, \mu_0) ,$$

$\tilde{Y}$  - a continuous function of the class  $C^1_{y,\bar{y},z}$  in a neighbourhood of the point  $y = 0, z = 0, 0 \leq \varepsilon < L, \mu \in \mathbb{M}$ . The second equation in (1.4) is conjugated to the first one in (1.4) and can be gained from this by the change  $y$  for  $\bar{y}$ ,  $\bar{y}$  for  $y$  and  $i$  for  $-i$ . Further equations which will be conjugated to another ones will not be written.

*Proof.* Expressing (1.1) in the form

$$(1.5) \quad \dot{x} = Px + Qx + X^1(x, \mu) + X^*(x, \mu)$$

and putting (1.3) into (1.5) we get:

$$S\dot{\xi} = P(S\xi + T\mu) + Q\mu + X^1(S\xi + T\mu, \mu) + X^*(S\xi + T\mu, \mu) .$$

From this we have:

$$(1.6) \quad \dot{\xi} = S^{-1}PS\xi + (S^{-1}PT + S^{-1}Q)\mu + S^{-1}X^1 + S^{-1}X^* .$$

If the matrices  $S, T$  are taken in the way to get:  $S^{-1}PS = \text{diag}(i\lambda, -i\lambda, J)$ ,  $T = -P^{-1}Q$ , then (1.6) gives the system (1.4). The proof is over.

Consider now the system

$$(1.7) \quad \begin{aligned} \dot{y} &= i\lambda y + Y(y, \bar{y}, z, \mu) \\ \dot{z} &= Jz + Z(y, \bar{y}, z, \mu) , \end{aligned}$$

which is gained from the system (1.4) by taking away the functions  $Y^*, Z^*$ .

**Lemma 1.2.** *Let the eigenvalues  $\lambda = (\lambda_1, \dots, \lambda_m)$  of the matrix  $P$  satisfy the condition:*

$$(1.8) \quad q_1\lambda_1 + \dots + q_m\lambda_m \neq 0 \quad \text{for} \quad 0 < |q| \leq 3p + 2 ,$$

$|q| = |q_1| + \dots + |q_m|$ ,  $q_i$  - integer numbers,  $i = 1, \dots, m$ .

There exists a polynomial transformation

$$(1.9) \quad \begin{aligned} y &= u + h(u, \bar{u}, \mu) \\ z &= v + g(u, \bar{u}, \mu) , \end{aligned}$$

where  $u = (u_1, \dots, u_m)$ ,  $v = (v_1, \dots, v_{n-2m})$ ,  $h, g$  are polynomials without scalar and linear terms, that reduces the system (1.7) to the system

$$(1.10) \quad \begin{aligned} \dot{u} &= i\lambda u + uU(u \cdot \bar{u}, \mu) + U^0(u, \bar{u}, v, \mu) + U^*(u, \bar{u}, v, \mu) \\ \dot{v} &= Jv + V^0(u, \bar{u}, v, \mu) + V^*(u, \bar{u}, v, \mu) , \end{aligned}$$

where  $U(u \cdot \bar{u}, \mu)$  - a vector polynomial with respect to  $u \cdot \bar{u}, \mu$  without scalar terms,  $U^0(u, \bar{u}, 0, \mu) = 0$ ,  $V^0(u, \bar{u}, 0, \mu) = 0$ ,  $U^*, V^*$  have the property (1.2).

*Proof.* Differentiating (1.9) with respect to  $t$  and taking into account (1.7) and (1.10) we obtain:

$$\begin{aligned} i\lambda(u+h) + Y(u+h, \bar{u} + \bar{h}, v+g, \mu) &= i\lambda u + uU + U^0 + U^* + \\ &+ \frac{\partial h}{\partial u}(i\lambda u + uU + U^0 + U^*) + \frac{\partial h}{\partial \bar{u}}(-i\lambda \bar{u} + \bar{u}\bar{U} + \bar{U}^0 + \bar{U}^*) \\ J(v+g) + Z(u+h, \bar{u} + \bar{h}, v+g, \mu) &= Jv + V^0 + V^* + \frac{\partial g}{\partial u}(i\lambda u + uU + U^0 + U^*) + \\ &+ \frac{\partial g}{\partial \bar{u}}(-i\lambda \bar{u} + \bar{u}\bar{U} + \bar{U}^0 + \bar{U}^*) . \end{aligned}$$

Giving away expressions with the property (1.2) and putting  $v = 0$  we get from these equations:

$$i\lambda u \frac{\partial h}{\partial u} - i\lambda \bar{u} \frac{\partial h}{\partial \bar{u}} - i\lambda h = Y(u+h, \bar{u} + \bar{h}, g, \mu) - uU \frac{\partial h}{\partial u} - \bar{u}\bar{U} \frac{\partial h}{\partial \bar{u}} - uU \quad (1.11)$$

$$i\lambda u \frac{\partial g}{\partial u} - i\lambda \bar{u} \frac{\partial g}{\partial \bar{u}} - Jg = Z(u+h, \bar{u} + \bar{h}, g, \mu) - uU \frac{\partial g}{\partial u} - \bar{u}\bar{U} \frac{\partial g}{\partial \bar{u}} .$$

Expressing the polynomials  $h, g$  in the form of the sum of vector homogenous polynomials  $h^{(s)}, g^{(s)}, s$  - the degree, we get from (1.11) that  $h^{(s)}, g^{(s)}$  are determined by the equations:

$$i\lambda u \frac{\partial h^{(s)}}{\partial u} - i\lambda \bar{u} \frac{\partial h^{(s)}}{\partial \bar{u}} - i\lambda h^{(s)} = P^{(s)}(h^{(i)}, g^{(j)}) - (uU)^{(s)} \quad (1.12)$$

$$i\lambda u \frac{\partial g^{(s)}}{\partial u} - i\lambda \bar{u} \frac{\partial g^{(s)}}{\partial \bar{u}} = R^{(s)}(h^{(i)}, g^{(j)}), \quad i < s, j < s .$$

We see that if we calculate  $h^{(s)}, g^{(s)}$  in the direction of arising  $s$  then the functions  $P^{(s)}, R^{(s)}$  will be known for every  $s$ . For the coefficients  $h_k^{(q, \tilde{q}, r)}, g_k^{(q, \tilde{q}, r)}$ ,  $q = (q_1, \dots, q_m)$ ,  $\tilde{q} = (\tilde{q}_1, \dots, \tilde{q}_m)$ ,  $r = (r_1, \dots, r_d)$  of the polynomials  $h^{(s)} = \text{col}(h_1^{(s)}, \dots, h_m^{(s)})$ ,  $g^{(s)} = \text{col}(g_1^{(s)}, \dots, g_{n-2m}^{(s)})$  we get from (1.12) the equations:

(1.13)

$$i \left[ \sum_{j=1}^m (q_j - \tilde{q}_j) \lambda_j - \lambda_k \right] h_k^{(q, \tilde{q}, r)} = P_k^{(q, \tilde{q}, r)} - U_k^{(q, \tilde{q}, r)}, \quad k = 1, \dots, m$$

(1.14)

$$i \left[ \sum_{j=1}^m (q_j - \tilde{q}_j) \lambda_j - \lambda_{2m+l} \right] g_l^{(q, \tilde{q}, r)} = R_l^{(q, \tilde{q}, r)}, \quad l = 1, \dots, n-2m.$$

When  $(q, \tilde{q}, r)$  is such a set that  $q_j = \tilde{q}_j$ ,  $q_k = \tilde{q}_k + 1$ ,  $j = 1, \dots, m$ ,  $j \neq k$ , then  $\sum_{j=1}^m (q_j - \tilde{q}_j) \lambda_j - \lambda_k = 0$  in (1.13). In this case we put  $U_k^{(q, \tilde{q}, r)} = P_k^{(q, \tilde{q}, r)}$  and  $h_k^{(q, \tilde{q}, r)} = 0$ . For other sets  $(q, \tilde{q}, r)$  in the power of (1.8)  $\sum_{j=1}^m (q_j - \tilde{q}_j) \lambda_j - \lambda_k \neq 0$ .

In these cases we put  $U_k^{(q, \tilde{q}, r)} = 0$ . Then the corresponding coefficient  $h_k^{(q, \tilde{q}, r)}$  is determined by equation (1.13) uniquely. The coefficients  $g_l^{(q, \tilde{q}, r)}$  in (1.14) are determined uniquely for every set of  $(q, \tilde{q}, r)$  as  $\sum_{j=1}^m (q_j - \tilde{q}_j) \lambda_j - \lambda_{2m+l} \neq 0$  since  $Re \lambda_{2m+l} \neq 0$ ,  $l = 1, \dots, n - 2m$ . The proof is over.

Let us perform the transformation (1.9) on the system (1.4). We again get system (1.10) but this time with another functions  $U^*, V^*$  having again the property (1.2). Introducing into this system polar coordinates

$$(1.15) \quad u = \rho e^{i\varphi}, \quad \bar{u} = \rho e^{-i\varphi},$$

$\rho = \text{col}(\rho_1, \dots, \rho_m)$ ,  $\varphi = \text{col}(\varphi_1, \dots, \varphi_m)$ ,  $e^{i\varphi} = \text{col}(e^{i\varphi_1}, \dots, e^{i\varphi_m})$ , we get:

$$(1.16) \quad \begin{aligned} \dot{\rho} &= \rho F(\rho^2, \mu) + F^0(\rho, \varphi, v, \mu) + F^*(\rho, \varphi, v, \mu) \\ \dot{\varphi} &= \lambda + \Phi(\rho^2, \mu) + \rho^{-1}[\Phi^0(\rho, \varphi, v, \mu) + \Phi^*(\rho, \varphi, v, \mu)] \\ \dot{v} &= Jv + V^0(\rho e^{i\varphi}, \rho e^{-i\varphi}, v, \mu) + V^*(\rho e^{i\varphi}, \rho e^{-i\varphi}, v, \mu), \end{aligned}$$

where  $\rho^2 = (\rho_1^2, \dots, \rho_m^2)$ ,  $\rho^{-1} = (\rho_1^{-1}, \dots, \rho_m^{-1})$ ,  $F = ReU(\rho^2, \mu)$ ,  $\Phi = ImU(\rho^2, \mu)$ ,  $F^0 + F^* = Re e^{-i\varphi}[U^0(\rho e^{i\varphi}, \rho e^{-i\varphi}, v, \mu) + U^*(\rho e^{i\varphi}, \rho e^{-i\varphi}, v, \mu)]$ ,  $\Phi^0 + \Phi^* = Im e^{-i\varphi}[U^0(\rho e^{i\varphi}, \rho e^{-i\varphi}, v, \mu) + U^*(\rho e^{i\varphi}, \rho e^{-i\varphi}, v, \mu)]$ ,  $F^0(\rho, \varphi, 0, \mu) = 0$ ,  $\Phi^0(\rho, v, 0, \mu) = 0$ ,  $F^*(\sqrt{\varepsilon}\rho, \varphi, \sqrt{\varepsilon}v, \varepsilon\mu_0) = (\sqrt{\varepsilon})^{3p+2}\tilde{F}(\rho, \varphi, v, \varepsilon, \mu_0)$ ,  $\Phi^*(\sqrt{\varepsilon}\rho, \varphi, \sqrt{\varepsilon}v, \varepsilon\mu_0) = \sqrt{\varepsilon}^{3p+2}\tilde{\Phi}(\rho, \varphi, v, \varepsilon, \mu_0)$ ,  $\tilde{F}$ ,  $\tilde{\Phi}$  - continuous functions with respect to all variables of the class  $C_{\rho, \varphi, v}^1$ . All functions in (1.16) depending on  $\varphi$  are  $2\pi$ -periodic with respect to all components of the vector  $\varphi$ .

Denote the linear parts of the function  $F(\rho^2, \mu)$  by the expression  $B\rho^2 + C\mu$ , where

$$B = \begin{pmatrix} B_{11} & \dots & B_{1m} \\ \dots & \dots & \dots \\ B_{m1} & \dots & B_{mm} \end{pmatrix}, \quad C = \begin{pmatrix} C_{11} & \dots & C_{1o} \\ \dots & \dots & \dots \\ C_{m1} & \dots & C_{mo} \end{pmatrix}.$$

The equation

$$(1.17) \quad B\rho^2 + C\mu = 0$$

is called the bifurcation equation of system (1.16).

Let us suppose that  $\det B \neq 0$  and that at least one element of the matrix  $C$  is different from zero.

Take an arbitrary  $\mu \in \mathbb{M}$ . The bifurcation equation (1.17) on the beam  $\delta(\mu_0) = \{\varepsilon\mu_0 : 0 \leq \varepsilon < L\}$  has the form:

$$B\rho^2 + \varepsilon C\mu_0 = 0.$$

Solving this equation with respect to  $\rho^2$  we have:

$$\rho^2 = \varepsilon(-B^{-1}C\mu_0) = \varepsilon\alpha^2(\mu_0) ,$$

where  $\alpha^2(\mu_0) = \text{col}[\alpha^2_1(\mu_0), \dots, \alpha^2_m(\mu_0)] = \Lambda\mu_0$  ,

$$\Lambda = \begin{pmatrix} \alpha_{11} & \dots & \alpha_{1o} \\ \dots & \dots & \dots \\ \alpha_{m1} & \dots & \alpha_{mo} \end{pmatrix} .$$

We say that the bifurcation equation (1.17) satisfies the condition of positiveness at  $\mu \in \mathbb{M}$  if  $\alpha^2(\mu_0)$  is positive at every component  $\alpha^2_k(\mu_0)$ ,  $k = 1, \dots, m$ . Let  $\mathcal{DP}$  denote the subset of all parameters  $\mu \in \mathbb{M}$  at which the bifurcation equation satisfies the condition of positiveness. We shall call this subset  $\mathcal{DP}$  the domain of positiveness of the bifurcation equation (1.17).

**Lemma 1.3.** *The domain of positiveness  $\mathcal{DP}$  of the bifurcation equation (1.17) is an open cone with the apex at the origin  $\mu = 0$  consisting of beams  $\delta(\mu_0) = \{\varepsilon\mu_0 : \mu \in \mathbb{M}, 0 < \varepsilon < L, \alpha^2_k(\mu_0) > 0, k = 1, \dots, m\}$ .*

*Proof.* Consider an arbitrary  $\mu^* \in \mathcal{DP}$  and take an arbitrary  $\mu \in \delta(\mu_0^*)$ ,  $\mu = \varepsilon\mu_0^*$ ,  $\varepsilon = \|\mu\|$ . As  $\alpha^2(\mu_0) = \text{col}[\alpha^2_1(\mu_0), \dots, \alpha^2_m(\mu_0)]$  and  $\alpha^2_k(\mu_0) = \frac{1}{\|\mu\|}(\alpha_{k1}\mu_1 + \dots + \alpha_{kd}\mu_d) = \frac{1}{\|\mu\|}(\alpha_{k1}\varepsilon\frac{\mu_1^*}{\|\mu^*\|} + \dots + \alpha_{kd}\varepsilon\frac{\mu_d^*}{\|\mu^*\|}) = \frac{1}{\|\mu^*\|}(\alpha_{k1}\mu_1^* + \dots + \alpha_{kd}\mu_d^*) = \alpha^2_k(\mu_0^*) > 0$ ,  $k = 1, \dots, m$ , we get that  $\delta(\mu_0^*) \subset \mathcal{DP}$ . This means that  $\mathcal{DP}$  is a cone. We need to show yet that to this  $\mu^*$  there exists such  $\sigma > 0$  that the sphere  $O_\sigma(\mu^*) \subset \mathcal{DP}$ . As  $\mu^* \in \mathcal{DP}$  so  $\alpha^2_k(\mu_0^*) = \nu_k > 0$ ,  $k = 1, \dots, m$ . Take an arbitrary  $\mu$  from a sphere  $O_\sigma(\mu^*)$ ,  $\mu \neq \mu^*$ . Then  $\alpha^2_k(\mu_0) = \frac{1}{\|\mu\|}(\alpha_{k1}\mu_1 + \dots + \alpha_{kd}\mu_d) = \frac{1}{\|\mu\|}[\alpha_{k1}(\mu_1^* + \sigma_1) + \dots + \alpha_{kd}(\mu_d^* + \sigma_d)]$ ,  $-\sigma < \sigma_j < \sigma$ ,  $j = 1, \dots, d$ ,  $k = 1, \dots, m$ . From this equation we have:

$$\alpha^2_k(\mu_0) > \frac{1}{\|\mu^*\| + \sigma}(\alpha_{k1}\mu_1^* + \dots + \alpha_{kd}\mu_d^*) - \frac{1}{\|\mu^*\| - \sigma}d\alpha\sigma ,$$

$$\alpha = \max\{|\alpha_{kl}|\}, \quad k = 1, \dots, m; \quad l = 1, \dots, d .$$

If we take  $\sigma = \frac{\|\mu^*\|}{s}$  then we get from the last inequality:

$$\alpha^2_k(\mu_0) > \frac{s}{s+1}\alpha^2_k(\mu_0^*) - \frac{d\alpha}{s-1} > \frac{s}{s+1}\nu - \frac{d\alpha}{s-1} > 0$$

for big enough natural number  $s$ ,  $\nu = \min\{\nu_1, \dots, \nu_m\}$ ,  $k = 1, \dots, m$ . The proof is over.

Let us take an arbitrary  $\mu \in \mathcal{DP}$ . On the beam  $\delta(\mu_0) = \{\varepsilon\mu_0 : 0 \leq \varepsilon < L\}$  the system (1.16) has the form:

$$(1.18) \quad \begin{aligned} \dot{\rho} &= \rho F(\rho^2, \varepsilon\mu_0) + F^0(\rho, \varphi, v, \varepsilon\mu_0) + F^*(\rho, \varphi, v, \varepsilon\mu_0) \\ \dot{\varphi} &= \lambda + \Phi(\rho^2, \varepsilon\mu_0) + \rho^{-1}[\Phi^0(\rho, \varphi, v, \varepsilon\mu_0) + \Phi^*(\rho, \varphi, v, \varepsilon\mu_0)] \\ \dot{v} &= Jv + V^0(\rho e^{i\varphi}, \rho e^{-i\varphi}, v, \varepsilon\mu_0) + V^*(\rho e^{i\varphi}, \rho e^{-i\varphi}, v, \varepsilon\mu_0) . \end{aligned}$$

The system (1.18) is the system of differential equations depending on one-dimensional non-negative parameter  $\varepsilon$  with the bifurcation equation satisfying the condition of positiveness. As it was shown in [1] the system (1.18) can be reduced introducing new variables  $x_1, \varphi_1, v_1$  by the relations  $\rho = \sqrt{\varepsilon}[\alpha(\mu_0) + x_1], \varphi = \varphi_1, v = \sqrt{\varepsilon}v_1$  to the system

$$\begin{aligned}
 \dot{x}_1 &= \varepsilon X_1(x_1, \varepsilon, \mu_0) + \sqrt{\varepsilon} X_1^0(x_1, \varphi_1, v_1, \varepsilon, \mu_0) + \\
 &\quad + (\sqrt{\varepsilon})^{3p+1} \tilde{X}_1(x_1, \varphi_1, v_1, \varepsilon, \mu_0) \\
 (1.19) \quad \dot{\varphi}_1 &= \lambda_1(\varepsilon) + \varepsilon \Phi_1(x_1, \varepsilon, \mu_0) + \sqrt{\varepsilon} \Phi_1^0(x_1, \varphi_1, v_1, \varepsilon, \mu_0) + \\
 &\quad + (\sqrt{\varepsilon})^{3p+1} \tilde{\Phi}_1(x_1, \varphi_1, v_1, \varepsilon, \mu_0) \\
 \dot{v}_1 &= Jv_1 + \sqrt{\varepsilon} V_1^0(x_1, \varphi_1, v_1, \varepsilon, \mu_0) + (\sqrt{\varepsilon})^{3p+1} \tilde{V}_1(x_1, \varphi_1, v_1, \varepsilon, \mu_0),
 \end{aligned}$$

where  $X_1, \Phi_1$  - vector polynomials,  $X_1(0, 0, \mu_0) = 0, \Phi_1(0, \varepsilon, \mu_0) = 0, \lambda(0) = \lambda, X_1^0, \Phi_1^0, V_1^0, \tilde{X}_1, \tilde{\Phi}_1, \tilde{V}_1$  - continuous functions in all variables of the class  $C_{x_1, \varphi_1, v_1}^1$  on the domain  $\mathbb{M}_1 = \{(x_1, \varphi_1, v_1, \varepsilon, \mu) : \|x_1\| < K_1, \|v_1\| < K_1, \varphi_1 \in \mathbb{R}^m, 0 \leq \varepsilon < L, \mu \in \mathcal{DP}\}$ ,  $X_1^0, \Phi_1^0, V_1^0$  vanishing at  $v_1 = 0$  and

$$(1.20) \quad P_1(\mu) = \frac{\partial X_1(0, 0, \mu_0)}{\partial x_1} = 2[\text{diag } \alpha(\mu_0)]B[\text{diag } \alpha(\mu_0)].$$

We say that  $P_1(\mu)$  is non-critical at  $\mu \in \mathcal{DP}$  if its eigenvalues do not lie on the imaginary axis and is critical at  $\mu \in \mathcal{DP}$  if it has at least one pair of pure imaginary eigenvalues while the others have non-zero real parts. Let  $\mathcal{DC}$  denote the subset of all parameters  $\mu \in \mathcal{DP}$  at which the matrix  $P_1(\mu)$  is critical. We shall call this subset  $\mathcal{DC}$  the domain of criticalness of the bifurcation equation (1.17).

**Theorem 1.1.** *To every  $\mu \in \mathcal{DP} \setminus \mathcal{DC}$  of the bifurcation equation (1.17) there exists the invariant manifold of the system (1.19) which is defined by the equations*

$$(1.21) \quad \begin{aligned} x_1 &= \|\mu\| \eta_1(\varphi_1, \|\mu\|, \mu_0) \\ v_1 &= \|\mu\|^2 \Theta_1(\varphi_1, \|\mu\|, \mu_0), \end{aligned}$$

where  $\eta_1(\varphi_1, \|\mu\|, \mu_0), \Theta_1(\varphi_1, \|\mu\|, \mu_0)$  are continuous functions  $2\pi$ -periodic in all components of  $\varphi_1, \varphi_1 \in \mathbb{R}^m, 0 \leq \|\mu\| < L, \mu \in \mathcal{DP} \setminus \mathcal{DC}$ . The natural number  $p$  in (1.2) can be taken  $p = 1$ .

*Proof.* Consider an arbitrary  $\mu \in \mathcal{DP} \setminus \mathcal{DC}$ . The parameter  $\mu$  lies on the beam  $\delta(\mu_0) = \{\varepsilon \mu_0 : 0 \leq \varepsilon < L\}$ . On this beam the system (1.16) can be reduced to the system (1.19). According to Theorem from section 3 of Chapter 1 in [1] there exists to every  $\varepsilon, 0 < \varepsilon < L$  (in the case of necessity  $L$  is taken smaller) the invariant manifold

$$\begin{aligned}
 x_1 &= \varepsilon \eta_1(\varphi_1, \varepsilon, \mu_0) \\
 v_1 &= \varepsilon^2 \Theta_1(\varphi_1, \varepsilon, \mu_0),
 \end{aligned}$$

where  $\eta_1, \Theta_1$  are continuous functions  $2\pi$ -periodic in all components  $\varphi_1, \varphi_1 \in \mathbb{R}^m, 0 \leq \varepsilon < L, p$  can be  $p = 1$ . In our case  $\varepsilon = \|\mu\|$ . The proof is over.



## 2. One pair of pure imaginary eigenvalues

Suppose that the eigenvalues of the matrix  $P$  of the system (1.1) are:  $\pm i\lambda$ ,  $\lambda_3, \dots, \lambda_n$ ,  $\operatorname{Re}\lambda_k \neq 0$ ,  $k = 3, \dots, n$ .

The bifurcation equation (1.17) of system (1.16) is:

$$(2.1) \quad B\rho^2 + C\mu = 0 ,$$

where  $B \in \mathbb{R}$ ,  $C = (C_1, \dots, C_d)$ ,  $C_k \in \mathbb{R}$ ,  $k = 1, \dots, d$ .

We suppose that  $B \neq 0$  and the vector  $C$  has at least one element different from zero.

**Theorem 2.1.** *If the matrix  $P$  of the system (1.1) has one pair of pure imaginary eigenvalues and the others have non-zero real parts then:*

1.  $\mathcal{DP}$  of the bifurcation equation (2.1) is the whole half-sphere of the sphere  $O = \{\mu = (\mu_1, \dots, \mu_d) : 0 < \|\mu\| < L\}$  which is determined by the hyperplane  $C_1\mu_1 + \dots + C_d\mu_d = 0$  and by a point  $\mu^* \in O$  at which  $-\frac{1}{B}(C_1\mu_1^* + \dots + C_d\mu_d^*) > 0$ .
2.  $\mathcal{DC}$  of the bifurcation equation (2.1) is empty set.

*Proof.* Let us take an arbitrary  $\mu \in \mathbb{M}$ . The bifurcation equation (2.1) has on the beam  $\delta(\mu_0) = \{\varepsilon\mu_0 : 0 \leq \varepsilon < L\}$  the form:  $B\rho^2 + \varepsilon C\mu_0 = 0$ . Solving this equation with respect to  $\rho^2$  we get:  $\rho^2 = \varepsilon\alpha^2(\mu_0)$ , where  $\alpha^2(\mu_0) = -\frac{1}{B\|\mu\|}(C_1\mu_1 + \dots + C_d\mu_d)$ .

$\mathcal{DP}$  is the set of all  $\mu \in \mathbb{M}$  at which

$$\alpha^2(\mu_0) = -\frac{1}{B\|\mu\|}(C_1\mu_1 + \dots + C_d\mu_d) > 0 .$$

From this inequality the first assertion of Theorem 2.1 follows.

The matrix  $P_1(\mu)$  of the system (1.19) has on  $\mathcal{DP}$  according to (1.20) this form:

$$P_1(\mu) = 2[\operatorname{diag} \alpha(\mu_0)] B[\operatorname{diag} \alpha(\mu_0)] = 2\sqrt{-\frac{1}{B\|\mu\|}(C_1\mu_1 + \dots + C_d\mu_d)} \cdot \\ B\sqrt{-\frac{1}{B\|\mu\|}(C_1\mu_1 + \dots + C_d\mu_d)} = -\frac{2}{\|\mu\|}(C_1\mu_1 + \dots + C_d\mu_d) \neq 0$$

for all  $\mu \in \mathcal{DP}$ . The proof is over.

**Consequence of Theorem 1.1 and Theorem 2.1.** To every  $\mu \in \mathcal{DP}$  of the bifurcation equation (2.1) there exists the invariant manifold of the system (1.19) of the kind (1.21).

### 3. Two pairs of pure imaginary eigenvalues

Suppose that the matrix  $P$  of the system (1.1) has two pairs of pure imaginary eigenvalues  $\pm i\lambda_1$ ,  $\pm i\lambda_2$  and the others  $\lambda_5, \dots, \lambda_n$  have non-zero real parts.

The bifurcation equation (1.17) of the system (1.16) is:

$$(3.1) \quad B\rho^2 + C\mu = 0 ,$$

where

$$B = \begin{pmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{pmatrix} , \quad C = \begin{pmatrix} C_{11} & \dots & C_{1d} \\ C_{21} & \dots & C_{2d} \end{pmatrix} .$$

We suppose that  $\det B \neq 0$  and the matrix  $C$  has at least one element different from zero.

Let us take an arbitrary  $\mu \in \mathbb{M}$ . The equation (3.1) has on the beam  $\delta(\mu_0) = \{\varepsilon\mu_0 : 0 \leq \varepsilon < L\}$  the form:  $B\rho^2 + \varepsilon C\mu_0 = 0$ . Solving this equation with respect to  $\rho^2$  we get

$$(3.2) \quad \rho^2 = \varepsilon(-B^{-1}C\mu_0) = \varepsilon\alpha^2(\mu_0) ,$$

where

$$\alpha^2(\mu_0) = \begin{pmatrix} \alpha_1^2(\mu_0) \\ \alpha_2^2(\mu_0) \end{pmatrix} = \Lambda\mu_0, \quad \Lambda = \begin{pmatrix} \alpha_1 \\ \alpha_2 \end{pmatrix} = \begin{pmatrix} \alpha_{11} & \dots & \alpha_{1d} \\ \alpha_{21} & \dots & \alpha_{2d} \end{pmatrix} .$$

The matrix  $P_1(\mu)$  which is defined by (1.20) has the form:

$$P_1(\mu) = 2 \begin{pmatrix} \alpha_1^2(\mu_0)B_{11} & \alpha_1(\mu_0)\alpha_2(\mu_0)B_{12} \\ \alpha_1(\mu_0)\alpha_2(\mu_0)B_{21} & \alpha_2^2(\mu_0)B_{22} \end{pmatrix} ,$$

where

$$\alpha_1(\mu_0) = \sqrt{\frac{1}{\|\mu\|}(\alpha_{11}\mu_1 + \dots + \alpha_{1d}\mu_d)}, \quad \alpha_2(\mu_0) = \sqrt{\frac{1}{\|\mu\|}(\alpha_{21}\mu_1 + \dots + \alpha_{2d}\mu_d)} .$$

**Lemma 3.1.** *The matrix  $P_1(\mu)$  is critical at  $\mu \in \mathcal{DP}$  only if the following two conditions are satisfied:*

$$(3.3) \quad \begin{aligned} 1. \quad & \det B > 0 \\ 2. \quad & a_1(\mu_0) = \alpha_1^2(\mu_0)B_{11} + \alpha_2^2(\mu_0)B_{22} = 0 . \end{aligned}$$

*Proof.* The characteristic equation of the matrix  $\frac{P_1(\mu)}{2}$  which is similar to  $P_1(\mu)$  is:

$$(3.4) \quad \lambda^2 - a_1(\mu_0)\lambda + a_2(\mu_0) = 0 ,$$

where  $a_1(\mu_0) = \text{Tr} \frac{P_1(\mu)}{2} = \alpha_1^2(\mu_0)B_{11} + \alpha_2^2(\mu_0)B_{22}$ ,  $a_2(\mu_0) = \det \frac{P_1(\mu)}{2} = \alpha_1^2(\mu_0)\alpha_2^2(\mu_0) \cdot \det B$ .

Comparing (3.4) with its expression by means of its pure imaginary roots we gain the conditions for  $P_1(\mu)$  to have a pair of pure imaginary eigenvalues:

$$a_1(\mu_0) = \alpha_1^2(\mu_0)B_{11} + \alpha_2^2(\mu_0)B_{22} = 0, \quad a_2(\mu_0) = \alpha_1^2(\mu_0)\alpha_2^2(\mu_0) \det B > 0 .$$

Taking into account that  $\alpha_1^2(\mu_0) > 0$ ,  $\alpha_2^2(\mu_0) > 0$  at every  $\mu \in \mathcal{DP}$  we get the assertion of Lemma 3.1.

**Theorem 3.1.** *Let the rank  $h(\Lambda)$  of the matrix  $\Lambda$  in (3.2) be 1. Then the following holds for  $\mathcal{DP}$  and  $\mathcal{DC}$  of the bifurcation equation (3.1):*

1.  $\mathcal{DP} \neq \emptyset \Leftrightarrow \alpha_2 = k\alpha_1, k > 0$ .
2.  $\mathcal{DC} \neq \emptyset \Leftrightarrow \{(\det B > 0) \wedge [(B_{11} = B_{22} = 0) \vee (B_{11} = -kB_{22})]\}$ .
3. If  $\mathcal{DC} \neq \emptyset \Rightarrow \mathcal{DC} \equiv \mathcal{DP}$ .

*Proof.* The domain of positiveness of the bifurcation equation (3.1) is determined by the inequalities:

$$\alpha_1^2(\mu_0) = \frac{1}{\|\mu\|}(\alpha_{11}\mu_1 + \dots + \alpha_{1d}\mu_d) > 0 \quad (3.5)$$

$$\alpha_2^2(\mu_0) = \frac{1}{\|\mu\|}(\alpha_{21}\mu_1 + \dots + \alpha_{2d}\mu_d) > 0 .$$

The first inequality in (3.5) is satisfied at all parameters  $\mu \in \mathbb{M}$  which belong to that half-sphere of the sphere  $O = \{\mu = (\mu_1, \dots, \mu_d) : 0 < \|\mu\| < L\}$  which is determined by the hyperplane  $\alpha_{11}\mu_1 + \dots + \alpha_{1d}\mu_d = 0$  and by a point  $\mu^* \in O$  at which  $\alpha_1^2(\mu_0^*) > 0$ . As  $h(\Lambda) = 1$  so there exists  $k \in \mathbb{R}$  such that  $\alpha_2 = k\alpha_1$ . Using this we can express the second inequality in (3.5) in the form:  $\frac{k}{\|\mu\|}(\alpha_{11}\mu_1 + \dots + \alpha_{1d}\mu_d) > 0$ . From this inequality it follows that the parameters  $\mu$  which satisfy the first inequality in (3.5) will also satisfy the second inequality in (3.5) only when  $k > 0$ . This gives the first assertion of Theorem 3.1.

Let  $\mathcal{DC} \neq \emptyset$ . Take an arbitrary  $\mu \in \mathcal{DP}$ . As  $\alpha_2 = k\alpha_1, k > 0$ , so  $\alpha_2^2(\mu_0) = k\alpha_1^2(\mu_0)$ . Therefore the conditions of criticalness (3.3) of the matrix  $P_1(\mu)$  can be written in the form:

$$\begin{aligned} 1. \quad & \det B > 0 \\ 2. \quad & a_1(\mu_0) = \alpha_1^2(\mu_0)(B_{11} + kB_{22}) = 0 . \end{aligned} \quad (3.6)$$

The equation (3.6) is satisfied only when  $B_{11} = B_{22} = 0$  or  $B_{11} = -kB_{22}$ . From this equation also follows that when  $B_{11} = B_{22} = 0$  or  $B_{11} = -kB_{22}$  then (3.6) is satisfied at every  $\mu \in \mathcal{DP}$ . This gives the second and the third assertion of Theorem 3.1. The proof is over.

**Theorem 3.2.** *Let the rank  $h(\Lambda)$  of the matrix  $\Lambda$  in (3.2) be 2. Then the following holds:*

1.  $\mathcal{DP} \neq \emptyset$
2.  $\mathcal{DC} \neq \emptyset \Leftrightarrow \{(\det B > 0) \wedge [(B_{11} = B_{22} = 0) \vee (B_{11}B_{22} < 0)]\}$
3.  $\mathcal{DC} \equiv \mathcal{DP} \Leftrightarrow [(\det B > 0) \wedge (B_{11} = B_{22} = 0)]$ .

*Proof.* As  $h(\Lambda) = 2$  then from the definition of the rank of a matrix follows that the dimension  $o$  of the parameter  $\mu$  is at least 2, i.e.  $o \geq 2$ . The domain of positiveness  $\mathcal{DP}$  of the equation (3.1) is determined by the inequalities

$$\frac{1}{\|\mu\|}(\alpha_{11}\mu_1 + \dots + \alpha_{1d}\mu_d) > 0 \quad (3.7)$$

$$\frac{1}{\|\mu\|}(\alpha_{21}\mu_1 + \dots + \alpha_{2d}\mu_d) > 0 .$$

Expressing (3.7) in the form of equations we get:

$$(3.8) \quad \begin{aligned} \alpha_{11}\mu_1 + \dots + \alpha_{1d}\mu_d - t_1 &= 0 \\ \alpha_{21}\mu_1 + \dots + \alpha_{2d}\mu_d - t_2 &= 0, \quad t_1 > 0, t_2 > 0. \end{aligned}$$

As the rank of the matrix of the system (3.8) is 2 this system has infinite number of solutions with  $t_1 > 0, t_2 > 0$ . Therefore the inequalities (3.7) have solutions  $\mu^* = (\mu_1^*, \dots, \mu_d^*)$ . As parameters  $\mu = \varepsilon\mu^*$  for  $0 < \varepsilon < L$  also satisfy (3.7) so  $\mathcal{DP} \neq \emptyset$ . This gives the first assertion of Theorem 3.2.

Let  $\mathcal{DC} \neq \emptyset$ . The conditions of the criticalness of the matrix  $P_1(\mu)$  are:

$$(3.9) \quad a_1(\mu_0) = \alpha_1^2(\mu_0)B_{11} + \alpha_2^2(\mu_0)B_{22}, \quad \det B > 0.$$

Let  $\mu^* \in \mathcal{DC}$ . It means that  $a_1(\mu_0^*) = 0$ ,  $\det B > 0$ . But as at the same time  $\mu^* \in \mathcal{DP}$  so  $\alpha_1^2(\mu_0^*) > 0$ ,  $\alpha_2^2(\mu_0^*) > 0$ . From (3.9) it follows that  $B_{11} = B_{22} = 0$  or  $B_{11}B_{22} < 0$ .

Let

$$(3.10) \quad (\det B > 0) \wedge [(B_{11} = B_{22} = 0) \vee (B_{11}B_{22} < 0)].$$

$\mathcal{DC}$  is the set of parameters  $\mu \in \mathcal{DP}$  satisfying the relations:

$$(3.11) \quad \begin{aligned} \alpha_{11}\mu_1 + \dots + \alpha_{1d}\mu_d &> 0 \\ \alpha_{21}\mu_1 + \dots + \alpha_{2d}\mu_d &> 0 \\ (\alpha_{11}\mu_1 + \dots + \alpha_{1d}\mu_d)B_{11} + (\alpha_{21}\mu_1 + \dots + \alpha_{2d}\mu_d)B_{22} &= 0. \end{aligned}$$

We shall show that under the assumptions (3.10) these relations have solutions. Expressing (3.11) in the form of equations we get:

$$(3.12) \quad \begin{aligned} \alpha_{11}\mu_1 + \dots + \alpha_{1d}\mu_d - t_1 &= 0 \\ \alpha_{21}\mu_1 + \dots + \alpha_{2d}\mu_d - t_2 &= 0 \\ (\alpha_{11}B_{11} + \alpha_{21})B_{22}\mu_1 + \dots + (\alpha_{1d}B_{11} + \alpha_{2d}B_{22})\mu_d &= 0. \end{aligned}$$

If  $B_{11} = B_{22} = 0$  then the third equation in (3.12) is satisfied for every  $\mu \in \mathcal{DP}$  and  $\mathcal{DC} \equiv \mathcal{DP}$ .

If  $B_{11}B_{22} < 0$  then the system (3.12) can be reduced to the form:

$$(3.13) \quad \begin{aligned} \alpha_{11}\mu_1 + \dots + \alpha_{1d}\mu_d - t_1 &= 0 \\ \alpha_{21}\mu_1 + \dots + \alpha_{2d}\mu_d - t_2 &= 0 \\ B_{11}t_1 + B_{22}t_2 &= 0. \end{aligned}$$

As  $h(\Lambda) = 2$  so the rank of the system (3.13) is 3. One of  $d - 1$  parameters of this system is  $t_2$ . For  $t_1$  we get:  $t_1 = -\frac{B_{22}}{B_{11}}t_2 > 0$  as  $t_2 > 0$ . So the system (3.13) has infinite number of solutions  $(\mu_1^*, \dots, \mu_d^*, t_1^*, t_2^*)$  with  $t_1^* > 0, t_2^* > 0$ . This means that at these solutions  $\alpha_1^2(\mu_0^*) > 0$ ,  $\alpha_2^2(\mu_0^*) > 0$  and  $a_1(\mu_0^*) = 0$ . Thus parameters

$\mu = \varepsilon\mu^*$ ,  $0 < \varepsilon < L$ , belong to  $\mathcal{DC}$  and therefore  $\mathcal{DC} \neq \emptyset$ . This gives the second assertion of Theorem 3.2 and the relation:  $[(\det B > 0) \wedge (B_{11} = B_{22} = 0)] \Rightarrow \mathcal{DC} \equiv \mathcal{DP}$ .

Suppose that  $\mathcal{DC} \equiv \mathcal{DP}$ . Consider the parameters  $\mu^*, \mu^+$  which are the solutions of (3.8) corresponding to the pairs  $(t_1^* = 1, t_2^* = 1)$ ,  $(t_1^+ = 1, t_2^+ = 2)$  respectively and an arbitrary choice of the other parameters of (3.8). Then we have from (3.8):

$$\begin{aligned}\alpha_{11}\mu_1^* + \dots + \alpha_{1d}\mu_d^* &= 1 \\ \alpha_{21}\mu_1^* + \dots + \alpha_{2d}\mu_d^* &= 1\end{aligned}$$

and also

$$\begin{aligned}\alpha_{11}\mu_1^+ + \dots + \alpha_{1d}\mu_d^+ &= 1 \\ \alpha_{21}\mu_1^+ + \dots + \alpha_{2d}\mu_d^+ &= 2.\end{aligned}$$

Take an arbitrary  $\varepsilon_0, 0 < \varepsilon_0 < L$  and consider the parameters  $\mu^*(\varepsilon_0) = \varepsilon_0\mu^* \in \mathcal{DP}$ ,  $\mu^+(\varepsilon_0) = \varepsilon_0\mu^+ \in \mathcal{DP}$ . According to the assumption  $\mathcal{DC} \equiv \mathcal{DP}$  we have:  $\mu^*(\varepsilon_0) \in \mathcal{DC}$ ,  $\mu^+(\varepsilon_0) \in \mathcal{DC}$ . Thus the conditions of criticalness at  $\mu^*(\varepsilon_0)$ ,  $\mu^+(\varepsilon_0)$  are satisfied what means:

$$(3.14) \quad \alpha_1^2[\mu_0^*(\varepsilon_0)]B_{11} + \alpha_2^2[\mu_0^*(\varepsilon_0)]B_{22} = 0$$

$$\alpha_1^2[\mu_0^+(\varepsilon_0)]B_{11} + \alpha_2^2[\mu_0^+(\varepsilon_0)]B_{22} = 0.$$

As  $\alpha_1^2[\mu_0^*(\varepsilon_0)] = \alpha_2^2[\mu_0^*(\varepsilon_0)] = \frac{1}{\|\mu^*\|}$  and  $\alpha_1^2[\mu_0^+(\varepsilon_0)] = \frac{1}{\|\mu^+\|}$ ,  $\alpha_2^2[\mu_0^+(\varepsilon_0)] = \frac{2}{\|\mu^+\|}$ , the equations (3.14) have the form:

$$\begin{aligned}\frac{1}{\|\mu^*\|}B_{11} + \frac{1}{\|\mu^*\|}B_{22} &= 0 \\ \frac{1}{\|\mu^+\|}B_{11} + \frac{2}{\|\mu^+\|}B_{22} &= 0.\end{aligned}$$

But this system is satisfied only when  $B_{11} = B_{22} = 0$ . This gives the relation:  $\mathcal{DC} \equiv \mathcal{DP} \Rightarrow [(\det B > 0) \wedge (B_{11} = B_{22} = 0)]$ . The proof of Theorem 3.2 is over.

According to Theorem 1.1 to every  $\mu \in \mathcal{DP} \setminus \mathcal{DC}$  there exists an invariant manifold (1.21) which is homeomorphic with an invariant torus. Suppose now that  $\mu \in \mathcal{DC}$  of the bifurcation equation (3.1). This means that  $P_1(\mu)$  is critical on the beam of parameters  $\delta(\mu_0) = \{\varepsilon\mu_0 : 0 \leq \varepsilon < L\}$ . On this beam the system

$$(3.15) \quad \dot{x}_1 = \varepsilon X_1(x_1, \varepsilon, \mu_0)$$

which is gained from the first equation of (1.19) is two-dimensional system with the critical matrix  $P_1(\mu) = \frac{\partial X_1(0,0,\mu_0)}{\partial x_1}$ . Denote its eigenvalues  $\pm i\lambda^1$ . The system (3.15) is the system of the same character as the system  $\dot{x} = X(x, \varepsilon, \mu_0)$  which is gained from the system (1.1) being expressed on the beam  $\delta(\mu_0)$ . As it was shown

in [1] we can do on (1.19) the analogical sequence of transformations as it was done on the system (1.1). During this process we get the bifurcation equation

$$(3.16) \quad B_1 \rho_1^2 + \varepsilon C_1(\mu_0) = 0, \quad B_1 \in \mathbb{R}, \quad C_1(\mu_0) \in \mathbb{R}.$$

If (3.16) satisfies the condition of positiveness, i.e.  $\rho_1^2 = \varepsilon[-\frac{1}{B_1}C_1(\mu_0)] = \varepsilon\alpha^2(\mu_0)$ ,  $\alpha^2(\mu_0) > 0$ , the system (1.19) can be reduced to the system

$$(3.17) \quad \begin{aligned} \dot{x}_2 &= \varepsilon^2 X_2(x_2, \varepsilon, \mu_0) + X_2^0(x_2, \varphi_{12}, \varphi_{22}, v_{12}, \varepsilon, \mu_0) + \\ &\quad + (\sqrt{\varepsilon})^{3p} \tilde{X}_2(x_2, \varphi_{12}, \varphi_{22}, v_{12}, \varepsilon, \mu_0) \\ \dot{\varphi}_{12} &= \lambda_1(\varepsilon) + \varepsilon^2 \Phi_{12}(x_2, \varepsilon, \mu_0) + \Phi_{12}^0(x_2, \varphi_{12}, \varphi_{22}, v_{12}, \varepsilon, \mu_0) + \\ &\quad + (\sqrt{\varepsilon})^{3p} \tilde{\Phi}_{12}(x_2, \varphi_{12}, \varphi_{22}, v_{12}, \varepsilon, \mu_0) \\ \dot{\varphi}_{22} &= \varepsilon \lambda_2(\varepsilon) + \varepsilon^2 \Phi_{22}(x_2, \varepsilon, \mu_0) + \Phi_{22}^0(x_2, \varphi_{12}, \varphi_{22}, v_{12}, \varepsilon, \mu_0) + \\ &\quad + (\sqrt{\varepsilon})^{3p} \tilde{\Phi}_{22}(x_2, \varphi_{12}, \varphi_{22}, v_{12}, \varepsilon, \mu_0) \\ \dot{v}_{12} &= J v_{12} + V_{12}^0(x_2, \varphi_{12}, \varphi_{22}, v_{12}, \varepsilon, \mu_0) + \\ &\quad + (\sqrt{\varepsilon})^{3p+1} \tilde{V}_{12}(x_2, \varphi_{12}, \varphi_{22}, v_{12}, \varepsilon, \mu_0), \end{aligned}$$

where  $\dim x_2 = \dim \varphi_{22} = 1$ ,  $\dim \varphi_{12} = 2$ ,  $\dim v_{12} = n - 4$ ,  $\lambda_1(0) = \lambda$ ,  $\lambda_2(0) = \lambda^1$  and the functions  $X_2, \Phi_{12}, \Phi_{22}, X_2^0, \Phi_{12}^0, \Phi_{22}^0, V_{12}^0, \tilde{X}_2, \tilde{\Phi}_{12}, \tilde{\Phi}_{22}, \tilde{V}_{12}$  have the same character as the analogical functions in (1.19).

Denote  $P_2(\mu) = \frac{\partial X_2(0,0,\mu_0)}{\partial x_2}$ . It was shown in [1] that  $P_2(\mu) = 2\alpha^2(\mu_0)B_1 = -2C_1(\mu_0)$ . As the bifurcation equation (3.16) satisfies the condition of positiveness we have  $P_2(\mu) \neq 0$  what means that  $P_2(\mu)$  is non-critical. Therefore according to Theorem of section 3 Chapter 1 in [1] the following assertion is valid.

**Theorem 3.3.** *Let  $\mu \in \mathcal{DC}$  of the bifurcation equation (3.1). If the bifurcation equation (3.16) satisfies at  $\mu$  the condition of positiveness then  $p$  in (1.2) can be taken  $p = 2$  and to this  $\mu$  there exists the invariant manifold of the system (3.17) which is defined by the equations*

$$\begin{aligned} x_2 &= \|\mu\| \eta_2(\varphi_{12}, \varphi_{22}, \|\mu\|, \mu_0) \\ v_{12} &= \|\mu\|^2 \Theta_2(\varphi_{12}, \varphi_{22}, \|\mu\|, \mu_0), \end{aligned}$$

where  $\eta_2, \Theta_2$  are continuous functions in all variables  $2\pi$ -periodic at  $\varphi_{12}, \varphi_{22}, \varphi_{12} \in \mathbb{R}^2, \varphi_{22} \in \mathbb{R}^1, 0 \leq \varepsilon < L$ .

## REFERENCES

- [1] Bibikov, Yu. N., *Multi - frequency non-linear oscillations and their bifurcations*, The Publishing House of the Saint Petersburg University, Saint Petersburg, 1991. (Russian)

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